



FaPN: Feature-aligned Pyramid Network for Dense Image Prediction

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Dense image prediction is a **pixel-level classification** task that includes semantic segmentation, object detection, instance segmentation, et.al.

Feature pyramid network for dense image prediction



- Spatial reduction with downsampling will make the features on the top have larger perceptive fileds as stronger semantics for better classification.
- Semantic backpropagation with upsampling aims to distribute the semantics back to their corresponding locations at each scale to achieve rich semantics at all levels.

- Step-by-step downsampling makes the features lose location details progressively and dramatically.
- When without any accurate location reference, non-learnable upsampling operations will misplace the semantic feature into the upscaled map, i.e., misaligned context.
- The locality of convolution and upsampling makes the scope of misaligned context is local in which the object boundaries will suffer from severe misclassification due to the ambiguous context.



Two examples to illustrate the misaligned boundaries:

Differences between the image and image after rescaled. The difference exists over object boundaries and the area of difference is increasing as the downsamping rate.



An example result from FPN.

FaPN: Feature-aligned pyramid network for dense image prediction



- Compared to FPN, our FaPN has two additional modules, i.e., FAM and FSM.
- Our FaPN is flexible and can be placed in any FPN-based method by simple replacement.

Feature alignment and selection modules

Feature alignment module (FAM):

$$\begin{aligned} \hat{\mathbf{P}}_{i}^{u} &= f_{a} \big(\mathbf{P}_{i}^{u}, \boldsymbol{\Delta}_{i} \big), \\ \boldsymbol{\Delta}_{i} &= f_{o} \big([\hat{\mathbf{C}}_{i-1}, \mathbf{P}_{i}^{u}] \big) \end{aligned}$$

 Learning the offsets from the differences between the detailed and upsampled features.

> Aligning upsampled features with the learned offsets.



Feature selection module (FSM):

$$\hat{\mathbf{C}}_{i} = f_{s}(\mathbf{C}_{i} + \mathbf{u} * \mathbf{C}_{i}),$$
$$\mathbf{u} = f_{m}(\mathbf{z}),$$

- Modeling the importance of each feature map in the detailed features.
- Emphasizing the detailed rich features by multiplying the importance values before channel reduction.



method	backbone	#Params (M)	mIoU (%)
FPN	R50	28.6 (+4.5)	77.4 (+2.6)
FPN + extra 3×3 conv.	R50	33.4 (-0.3)	77.5 (+2.5)
FPN	R101	47.6 (-14.5)	78.9 (+1.1)
FPN + FAM	R50	31.7 (+1.4)	79.7 (+0.3)
FPN + FAM + SE	R50	33.1 (+0.0)	78.8 (+1.2)
FPN + FAM + FSM (FaPN)	R50	33.1 (+0.0)	80.0 (+0.0)
FPN + deconv + FSM	R50	32.7 (+0.4)	76.7 (+3.3)
$FPN + FAM^{\dagger} + FSM$	R50	32.7 (+0.4)	79.3 (+0.7)

- # 2~3: Additional learnable parameters in FPN would not boost the performance greatly as our FaPN.
- # 4~5: FAM is compatible with FSM, while the SE module adversely affects the performance.
- # 7: Replacing the non-learnable upsampling with a learnable one could not improve the performance, i.e., addressing feature misalignment
- ➢ # 8: Location reference matters during alignment.

method	backbone	3px	5px	8px	12px	mean
FPN	PointPond [21]	46.9	53.6	59.3	63.8	55.9
FaPN	Pointkend [21]	49.2	56.2	62.0	66.4	58.5
improvement	K30	(+2.3)	(+2.6)	(+2.7)	(+2.6)	(+2.6)
FPN	PointPond [21]	47.8	54.6	60.5	64.9	57.0
FaPN	R101	50.1	57.1	62.9	67.2	59.3
improvement		(+2.3)	(+2.5)	(+2.4)	(+2.3)	(+2.3)

Segmentation performance around boundaries

Both the quantitative evaluation and qualitative observation are consistent:

- Compared with FPN, FaPN achieves higher mIoU over the boundary segmentation.
- Raw upsampled features are noisy and fluctuating, while the aligned features are smooth and containing more precise object boundaries.



Visualization of the input to and the output from FAM

Main results



- > Our FaPN can be applied in four dense image prediction tasks.
- A simple replacement of FPN with FaPN in five representative methods yields an overall improvement of 1.2 - 2.6 points in AP / mIoU.
- > Our FaPN mainly improves the performance of small objects.

Example prediction visualizations



- Compared to FPN, FaPN significantly improves the performance of small objects.
- ➢ FaPN also has finer segmentation on object boundaries.

method	backbone	crop size	mIoU (s.s.)	mIoU (m.s.)
OCRNet [49]	R101	520×520	-	45.3
AlignSeg [17]	R101	512×512	-	46.0
SETR [51]	ViT-L [†]	512×512	-	50.3
Swin-UperNet [27]	Swin-L [†]	640×640	-	53.5
MaskFormer [8]	Swin-L [†]	640×640	54.1	55.6
MaskFormer + FaPN	Swin-L [†]	640×640	55.2	56.7

(a) ADE20K val

(b) COCO-Stuff-10K test

method	backbone	crop size	mIoU (s.s.)	mIoU (m.s.)
OCRNet [49]		520×520	-	39.5
MaskFormer [8]	R101	640×640	38.1	39.8
MaskFormer + FaPN		640×640	39.6	40.6

- Our FaPN is also efficient and applied to real-time segmentation methods.
- A simple replacement of FPN with our FaPN achieves competitive results against existing dedicated methods.

- Our FaPN also advances the Transformer-based methods.
- When augmented with MaskFormer, our FaPN achieves the 2nd best result over ADE20k-150.

method	backbone	crop size	FPS	mIoU (val)	mIoU (test)
ESPNet [36]	†	512×1024	113	-	60.3
ESPNetV2 [37]	†	512×1024	-	66.4	66.2
FaPN	R18	512×1024	142	69.2	68.8
BiSeNet [49]	R18	768×1536	65.6	74.8	74.7
FaPN	R18	768 imes 1536	78.1	75.6	75.0
SwiftNet [39]	R18	1024×2048	39.9	75.4	75.5
ICNet [51]	R50	1024×2048	30.3	-	69.5
FaPN	R34	1024×2048	30.2	78.5	78.1

(a) Cityscapes

h)	COCO Stuff 10V	
U)	COCO-Stull-10K	

method	backbone	crop size	FPS	mIoU (val)
BiSeNet [49]	R18		-	28.1
BiSeNetV2 [48]	†		42.5	28.7
ICNet [51]	R50	640×640	35.7	29.1
FaPN	R18	·	154	28.4
FaPN	R34		110	30.3

Thanks!

The code is available at: <u>https://github.com/ShihuaHuang95/FaPN-full</u>

